

# FUJI SERVO SYSTEM **ALPHA5 Smart**



## NEW Middle Inertia Type GYB Series Servo Motor (Rated speed 3000r/min)

Wildule ille	illa Type GTD	Series Servo Motor (Hat	ed speed 30001/11111)
Voltage	Rated output	Motor Type (Standard)	Amplifier Type
Ü	0.2kW	GYB201D5-□□2 (-B)	RYH201F5-VV2
Single or 3-phase 200V	0.4kW	GYB401D5-□□2 (-B)	RYH401F5-VV2
	0.75kW	GYB751D5-□□2 (-B)	RYH751F5-VV2



## Middle Inertia Type GYG Series Servo Motor (Rated speed 2000r/min)

Voltage	Rated output	Motor Type (Standard)	Amplifier Type
Single or	0.5kW	GYG501C5-□□2 (-B)	RYH751F5-VV2
3-phase 200V	0.75kW	GYG751C5-□□2 (-B)	RYH751F5-VV2
	1.0kW	GYG102C5-□□2 (-B)	RYH152F5-VV2
3-phase 200V	1.5kW	GYG152C5-□□2 (-B)	RYH152F5-VV2
	2.0kW	GYG202C5-□□2 (-B)	RYH202F5-VV2

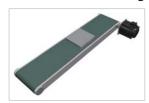


#### Contents Main Products/Combination table\_\_\_\_ 2 Servo Motor External Dimensions \_\_\_\_\_ 11 Features\_\_\_\_\_ 3 Optional Shaft Extension Specifications [with key, tapped] \_\_\_\_\_13 Product Family\_\_\_\_\_ 4 Configuration Diagram/ Peripheral Equipment \_\_\_\_\_14 Model Codes\_\_\_ Servo Amplifier Specifications/ Options \_\_\_\_\_\_15 External Dimensions \_\_\_\_\_\_6 Model List \_\_\_\_\_\_16 Servo Amplifier Interface Specifications/ Connection Diagram\_\_\_\_ Service Network \_\_\_\_\_\_18 Servo Motor Specifications \_\_\_\_\_ 8 Product Warranty\_\_\_\_\_19



#### Wide Range of Applications Feature 1

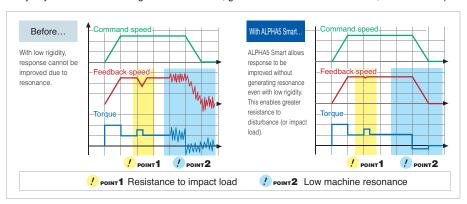
#### With the new auto-tuning function, optimal tuning can be realized even for low-rigidity devices!!





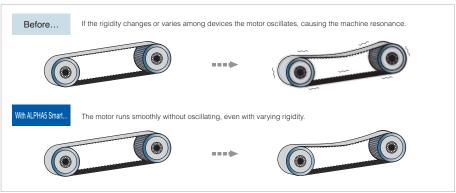


Easy adjustment even for long belt mechanisms, gears with considerable backlash, and rack and pinion mechanisms.



#### Super Stability Feature 2

#### Smooth, stable operation even with changes due to wear or variation\* among devices.



<sup>\*</sup> Variations in device rigidity such as belt tension or parts.

#### Other Features

smarter

## **Smart Operation**

New handy-sized portable servo operator makes the operation much



## ... Long-life design

Electrolytic capacitor 10years Cooling fan 10years

- \* Operating conditions
- Ambient temperature: Average 30°C/year
- Load factor: Within 80%
- Operation rate: Within 20 hours/day

## Easy ABS battery replacement

ABS backup battery can be mounted on front face of servo amplifier for easy replacement

## ■ Regulatory compliance

Global Compatibility. The standard model complies with CE marking, UL/cUL and TÜV.







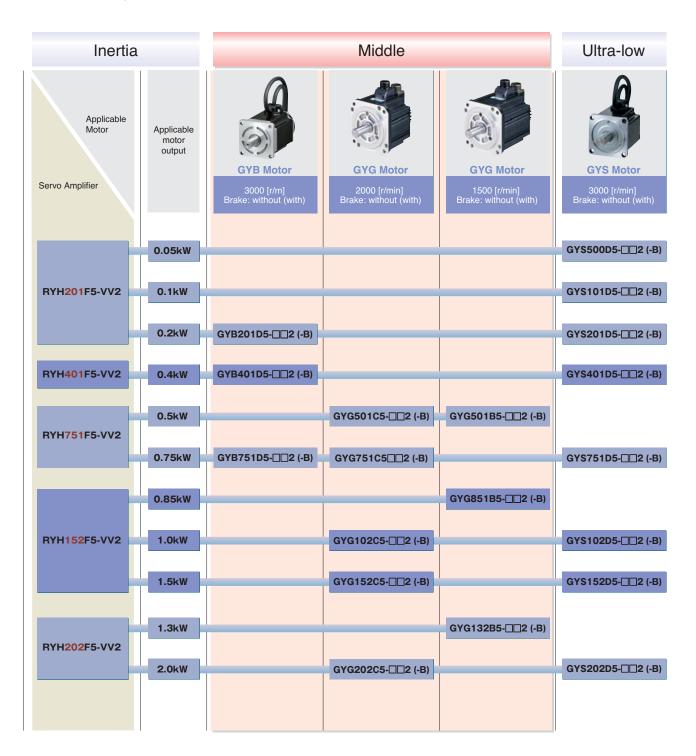
\* Some of the models are in the process to be certified.

#### **:::** RoHS Directive

Compliant with the European Restriction of Hazardous Substances (ROHS) Directive. The use of six hazardous substances has been reduced for a more environmentally-friendly servo system.

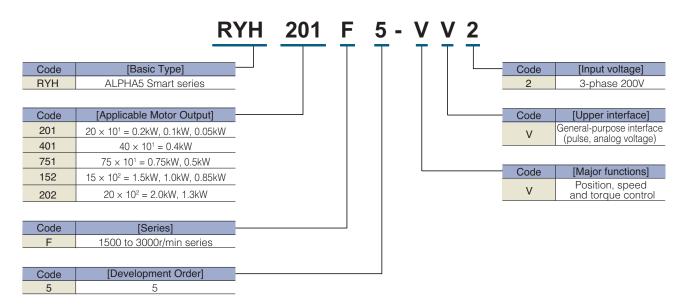
<Six hazardous materials> Lead, mercury, cadmium, hexavalent chromium, polybrominated biphenyl (PBB), polybrominated diphenylether (PBDE)

# Servo Amplifier / Motor

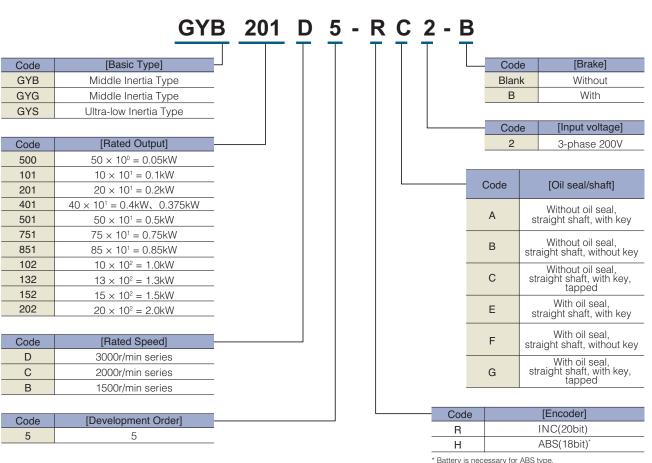




# Servo Amplifier



## Servo Motor

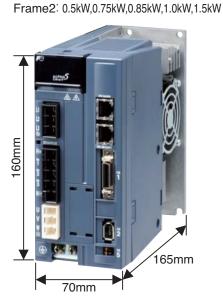


Note: Please see the model list on page 16, 17 for the combination detail.

Frame3: 1.3kW,2.0kW

Frame1: 0.05kW,0.1kW,0.2kW,0.4kW







## **:::** Common specifications

Applicable moto	r rated s	speed				3000	)r/min						2000r/min				1500r/mir	1
Applicable moto	r output	[kW]	0.05	0.1	0.2	0.4	0.75	1.0	1.5	2.0	0.5	0.75	1.0	1.5	2.0	0.5	0.85	1.3
Amplifier type	RYH	F5-VV2		201		401	751	15	52	202	75	51	15	2	202	751	152	202
Outer frame numb	ber			1a		1b	2a	2	!b	3a	2	a	21	b	3a	2a	2b	3a
Mass		[kg]		0	.8		1.2	1.	.3	2.2	1	.2	1.	3	2.2	1.2	1.3	2.2
Protective constru	uction / c	ooling		Open / natural cooling				Ope	n / mech	anical coc	ling							
Power supply	Phase		Single-phase, 3-phase 3-phase 5			Single-pha	se, 3-phase		3-phase		Single-phase, 3-phase	3-ph	nase					
	Voltage	/ frequency	200 to 2	0 to 240VAC 50/60Hz														
	Allowable	voltage fluctuation	3-phase	phase : 170 to 264 VAC, Single-phase : 180 to 264 VAC														
Control system			Fully-di	gital sinu	soidal PV	/M drive												
Max voltage for regene-	Built-in	resistor		-	-			20		30		2	20		30	2	20	30
rative resistance [W]	Externa	al resistor		1	7			50		260		5	50		260	5	0	260
Feedback			INC 20b	INC 20bit/rev, ABS/INC 18bit/rev														
Overload capabili			300% /	300% / 3 sec.														
Speed fluctuation	Load fli	uctuation	Within ±	/ithin ± 0.01% (load fluctuation 0 to 100% at rated operation speed)														
ratio*	Power su	upply fluctuation	0% (po	0% (power supply fluctuation -10 to +10% at rated operation speed)														
	Tempera	ture fluctuation	Within ±	£ 0.2% (2	5 ± 10°C	at rated	operation	speed)										
Capability and	Speed	control	Closed	loop cont	rol with sp	eed adju	ster, acce	leration/de	eceleratio	n time set	ting, manı	ual feed ra	ate/max. rc	tation sp	eed, spe	ed comma	nd zero c	lamp, etc.
function		f position data sets	15-poin	t (positio	n, speed	accelera	ation/dece	eleration t	ime settir	g, timer,	M code a	ınd variou	us statuse:	s)				
VV type		n control											ard, homir					
	- 4	control					,						rque), toro				ue contro	I, etc.
		ory functions								<u> </u>			suppress			<u> </u>		
Protective function	n				. ,.			0	0 1 /		,	. ,.	Circuit Tr					
(Alarm display)					. , , .								ONTrol si	,	. ,.			
					. ,				l3), Over	Flow (oF)	, Amp He	at (AH), E	Encoder H	leat (EH)	, Absolut	e Data Lo	st (dL1,	dL2, dL3)
						. ,.	ial Error (il	,										
Operation and display s		,, ,, ,										SET, UP a	and DOWN	1)				
Working	Installa	ition place					rom dust,		0		_							
conditions				ase of compliance with CE marking: pollution degree 2, over voltage category III														
		ture / humidity		to 55°C/10 to 90%RH (without condensation)														
	Vibratio						lz or less,	9.8m/s <sup>2</sup> :	9 to 20Hz	or less,	2m/s <sup>2</sup> : 20	to 55Hz	or less, 1n	n/s²: 55 to	200Hz	or less		
	shock r	resistance			e: 19.6m/	- ( - /												
Standards			UL/cUL	(UL508c	;), CE ma	rking (lov	v voltage	directive	EN61800	-5-1), Ro	HS direct	ive (Some	e of the mo	odels are	in the p	rocess to	be certisf	ied.)

<sup>&#</sup>x27;This value represents the average value of the speed fluctuation that is generated from load fluctuation, power supply fluctuation, and temperature fluctuation as the percentage to the rated rotation speed.

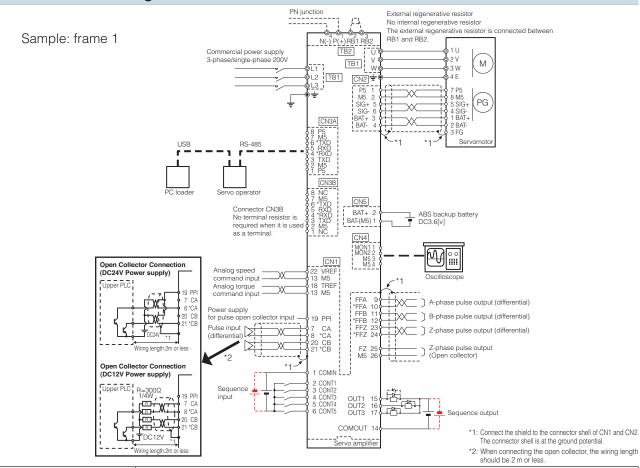


## **Interface Specifications**

Terminal name	Symbol	Specifications					
Pulse input	CA,*CA	Differential input: max. input frequency ≤ 1.0MHz					
	CB,*CB	Open collector input: max. input frequency ≤ 200kHz					
		(in case of signals at 90-degree phase difference,					
		the above relationship is true for the four-fold frequency.)					
		Pulse format					
		Command pulse/Command direction ) Select one of these formats					
		Forward/Reverse pulse					
		Two signals at 90-degree phase difference with a parameter setting.					
	PPI	Pull-up power input at open collector input (24VDC ± 5%)					
Pulse output	FFA,*FFA	Differential output: max. output frequency ≤ 1MHz					
	FFB,*FFB	Two signals at 90-degree phase difference					
		Pulse output count setting n (pulses/rev): 16 ≤ n ≤ 262144					
	FFZ,*FFZ	Differential output: 1 pulse/rev					
	FZ	Open collector output: 1 pulse/rev					
	M5	Reference potential (0V)					
Analog monitor	MON1	0V to ± 10VDC					
voltage output	MON2	Resolution: 14bits / ± full scale					
		The output data depends on internal parameter.					
	M5	Reference potential (0V)					
Common for	COMIN	Common for sequence input signal					
sequence I/O	COMOUT	Common for sequence output signal					
Sequence input signal	CONT1 to	12VDC-10% to 24VDC+10%					
	CONT5	Current consumption 8mA (per contact; used at circuit voltage of 12 to 24VDC)					
		Function of each signal depends on parameter setting					
		Compatible with both sink and source input methods					
	COMIN	Reference potential					
Sequence output signal	OUT1 to	30VDC / 50mA (max.)					
	OUT3	Function of each signal depends on parameter setting					
		Compatible with both sink and source output methods					
	COMOUT	Reference potential					
Analog voltage input	VREF	Speed command voltage input					
(for speed and torque control)		Input range: from -10 to 0 to -10V, input impedance 20kΩ Resolution: 15 bits / ± full scale					
	TREF	Torque command voltage input					
		Input range: from -10 to 0 to +10V, input impedance 20kΩ Resolution: 14 bits / ± full scale					
	M5	Reference potential (0V)					

Item		Specifications				
Command interface	Positioning function	RS-485 (Modbus-RTU), Di/Do				
	Position control	Pulse input				
	Speed control	Analog voltage input				
	Torque control	Analog voltage input				
Communication	on interface	Two RS-485 ports (for parameter editing and monitor)				
		Fuji's original protocol Modbus-RTU				
		9600/19200/38400/115200 bps, connection of max. 31 units				

## **WV Connection Diagram**





The diagram shown above is given as a reference for model selection. When actually using the selected servo system, make wiring connections according to the connection diagram and instructions described in the user's manual.

## **Middle Inertia GYB Motor [3000r/min]**

■Standard specifications

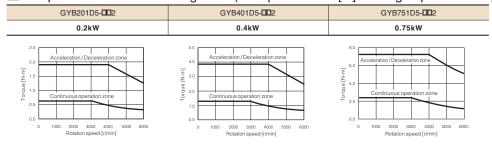
Motor type (-B) indicates the brake-incorporated type.	GYB201 D5-□□2 (-B)	GYB401 D5-□□2 (-B)	GYB751 D5-□□2 (-B)					
Rated output [kW]	0.2	0.4	0.75					
Rated torque [N · m]	0.637	1.27	2.39					
Rated speed [r/min]	3000							
Max. speed [r/min]	6000*1							
Max. torque [N · m]	1.91	3.82	7.17					
Inertia [kg · m²]	0.24 × 10 <sup>-4</sup>	$0.42 \times 10^{-4}$	1.43 × 10 <sup>-4</sup>					
( ) indicates brake-incorporated type.	$(0.29 \times 10^{-4})$	$(0.46 \times 10^{-4})$	$(1.61 \times 10^{-4})$					
Rated current [A]	1.5	2.7	5.2					
Max. current [A]	4.5	8.1	15.6					
Winding insulation class	Class B							
Degree of enclosure protection	Totally enclosed, self-cooled (IP 67. excluding t	Totally enclosed, self-cooled (IP 67. excluding the shaft-through)*2						
Terminals (motor)	0.3m cable	0.3m cable						
Terminals (encoder)	0.3m cable							
Overheat protection	Not provided (The servo amplifier detects temperature)	erature.)						
Mounting method	By securing motor flange IMB5 (L51), IMV1 (L52	2), IMV3 (L53)						
Encoder	18-bit serial encoder (absolute/incremental), 20-	-bit serial encoder (incremental)						
Vibration level	V5 or below							
Installation place, altitude and environment	For indoor use (free from direct sunlight), 1000n	n or below, locations without corrosive and flamab	ole gases, oil mist and dust					
Ambient temperature, humidity	-10 to +40°C, within 90% RH (without condensation)							
Vibration resistance [m/s²]	49							
Mass [kg]	1.0	1.5	3.0					
( ) indicates brake-incorporated type.	(1.5)	(1.5) (2.1) (3.9)						
Compliance with standards	UL/cUL (UL508c) (Some models are in the proc	ess to be certified), CE marking (low power direc	tive EN61800-5-1), RoHS directive.					

<sup>\*1:</sup> The max. speed of 5000r/min can be reached by using it with Fuji's gear head

#### ■Brake specifications (motor equipped with a brake)

		` • • •	•	
Motor type		GYB201 D5-□□2-B	GYB401 D5-□□2-B	GYB751 D5-□□2-B
Static friction torque	[N · m]	1.	27	2.45
Rated DC voltage	[V]	DC24±10%		
Attraction time	[ms]	4	0	60
Release time	[ms]	2	20	25
Power consumption	[W]	7.2 (at	20 °C)	8.5 (at 20 °C)

## ■Torque characteristics diagrams (at 3-phase 200 [V] or single-phase 230 [V] source voltage)



These characteristics indicate typical values of each servomotor combined with the corresponding servo amplifier RYH series.

The rated torque indicates the value obtained when the servo amplifier is installed to the following aluminum heat sink.

· Model GYB201, 401 : 250 × 250 × 6 [mm] · Model GYB751 : 300 × 300 × 6 [mm]

<sup>\*2:</sup> Protection degree IP67 is initial value



## **Middle Inertia GYG Motor [2000r/min, 1500r/min]**

#### ■Standard specifications

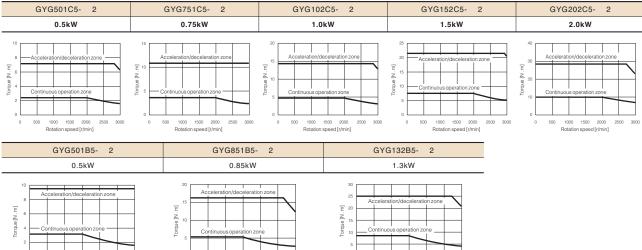
Motor type (-B) indicates the brake-incorporated type.	GYG501C5 -□□2 (-B)	GYG751C5 -□□2 (-B)	GYG102C5 -□□2 (-B)	GYG152C5 -□□2 (-B)	GYG202C5 -□□2 (-B)	GYG501B5 -□□2 (-B)	GYG851B5 -□□2 (-B)	GYG132B5 -□□2 (-B)	
Rated output [kW]	0.5	0.75	1.0	1.5	2.0	0.5	0.85	1.3	
Rated torque [N · m]	2.39	3.58	4.77	7.16	9.55	3.18	5.41	8.28	
Rated speed [r/min]		2000 1500							
Max. speed [r/min]	3000								
Max. torque [N · m]	7.2	10.7	14.3	21.5	28.6	9.5	16.2	24.8	
Inertia [kg · m <sup>2</sup> ]	7.96 × 10 <sup>-4</sup>	11.55 × 10 <sup>-4</sup>	15.14 × 10 <sup>-4</sup>	22.33 × 10 <sup>-4</sup>	29.51 × 10 <sup>-4</sup>	11.55 × 10 <sup>-4</sup>	15.15 × 10 <sup>-4</sup>	22.33 × 10 <sup>-4</sup>	
( ) indicates brake-incorporated type.	(10.0 × 10 <sup>-4</sup> )	(13.6 × 10 <sup>-4</sup> )	(17.2 × 10 <sup>-4</sup> )	(24.4 × 10 <sup>-4</sup> )	(31.6 × 10 <sup>-4</sup> )	(13.6 × 10 <sup>-4</sup> )	(17.3 × 10 <sup>-4</sup> )	$(24.5 \times 10^{-4})$	
Rated current [A]	3.5	5.2	6.4	10.0	12.3	4.7	7.3	11.5	
Max. current [A]	10.5	15.6	19.2	30.0	36.9	14.1	21.9	34.5	
Winding insulation class	Class F	lass F							
Degree of enclosure protection	Totally enclosed,	Fotally enclosed, self-cooled (IP 67. excluding the shaft-through)*2							
Terminals (motor)	Cannon connecto	or							
Terminals (encoder)	Cannon connecto	or							
Overheat protection	Not provided (The	e servo amplifier d	etects temperature	e.)					
Mounting method	By securing moto	r flange IMB5 (L51	I), IMV1 (L52), IMV	'3 (L53)					
Encoder	18-bit serial enco	der (absolute/incre	emental), 20-bit se	rial encoder (increi	mental)				
Vibration level	V10 or below								
Installation place, altitude and environment	For indoor use (fr	ee from direct sun	light), 1000m or be	low, locations with	out corrosive and	flamable gases, oi	I mist and dust		
Ambient temperature, humidity	-10 to +40°C, with	nin 90% RH (withou	ut condensation)						
Vibration resistance [m/s²]	24.5	24.5							
Mass [kg]	5.3	6.4	7.5	9.8	12.0	6.4	7.5	9.8	
( ) indicates brake-incorporated type.	(7.5)	(8.6)	(9.7)	(12.0)	(14.2)	(8.6)	(9.7)	(12.0)	
Compliance with standards	UL/cUL (UL1004)	, CE marking (EN6	60034-1, EN60034-	5), RoHS directive					

<sup>\*1</sup> The load inertia ratio to the inertia of servo motor. If the moment of load inertia ratio value exceeds the list value, please contact us.
\*2 If the motor is used in the environment rated to IP67 protection degree, use the wiring connector suitable for the protection degree.

## ■Brake specifications (motor equipped with a brake)

Motor type		GYG501C5 -□□2-B	GYG751C5 -□□2-B	GYG102C5 -□□2-B	GYG152C5 -□□2-B	GYG202C5 -□□2-B	GYG501B5 -□□2-B	GYG851B5 -□□2-B	GYG132B5 -□□2-B
Static friction torque	[N · m]	17							
Rated DC voltage	[V]	DC24±10%							
Attraction time	[ms]	120							
Release time	[ms]	30							
Power consumption	[W]	12 (at 20 °C)							

## ■Torque characteristics diagrams (at 3-phase 200 [V] or single-phase 230 [V] source voltage)



These characteristics indicate typical values of each servomotor combined with the corresponding servo amplifier RYH series. The rated torque indicates the value obtained when the servo amplifier is installed to the following aluminum heat sink.

· Model GYG501C, 751C, 102C : 300 ×300 ×12 [mm] Model GYG152C, 202C : 400 ×400 ×12 [mm] Model GYG501B, 851B : 300 ×300 ×12 [mm] · Model GYG132B : 400 ×400 ×12 [mm]

## **III Ultra-low Inertia GYS Motor [3000r/min]**

## ■Standard specifications

Motor type (-B) indicates the brake-incorporated type.	GYS500D5 -□□2 (-B)	GYS101D5 -□□2 (-B)	GYS201D5 -□□2 (-B)	GYS401D5 -DD2 (-B)	GYS751D5 -□□2 (-B)	GYS102D5 -□□2 (-B)	GYS152D5 -□□2 (-B)	GYS202D5 -□□2 (-B)
Rated output [kW]	0.05	0.1	0.2	0.4	0.75	1.0	1.5	2.0
Rated torque [N · m]	0.159	0.318	0.637	1.27	2.39	3.18	4.78	6.37
Rated speed [r/min]	3000							
Max. speed [r/min]			6000 *1				5000	
Max. torque [N · m]	0.478	0.955	1.91	3.82	7.17	9.55	14.3	19.1
Inertia [kg · m²]	0.0192×10 <sup>-4</sup>	0.0371×10 <sup>-4</sup>	0.135×10 <sup>-4</sup>	0.246×10 <sup>-4</sup>	0.853×10 <sup>-4</sup>	1.73×10 <sup>-4</sup>	2.37×10 <sup>-4</sup>	3.01×10 <sup>-4</sup>
( ) indicates brake-incorporated type.	(0.0223×10 <sup>-4</sup> )	(0.0402×10 <sup>-4</sup> )	(0.159×10 <sup>-4</sup> )	(0.270×10 <sup>-4</sup> )	(0.949×10 <sup>-4</sup> )	(2.03×10-4)	(2.67×10 <sup>-4</sup> )	(3.31×10 <sup>-4</sup> )
Rated current [A]	0.85	0.85	1.5	2.7	4.8	7.1	9.6	12.6
Max. current [A]	2.55	2.55	4.5	8.1	14.4	21.3	28.8	37.8
Winding insulation class			Class B	•		Class F		
Degree of enclosure protection	Totally enclos	sed, self-cooled (II	P 67. excluding the	shaft-through and	connectors)	Totally enclosed, self-	-cooled (IP 67. excluding	ng the shaft-through)*2
Terminals (motor)		Cabl	e 0.3m (with conne	ector)			Cannon connector	f
Terminals (encoder)		Cabl	e 0.3m (with conne	ector)		Cannon connector		
Overheat protection	Not provided (The	servo amplifier d	letects temperature	e.)				
Mounting method	By securing moto	r flange IMB5 (L5	1), IMV1 (L52), IMV	'3 (L53)				
Encoder	18-bit serial encode	der (absolute/incre	emental), 20-bit se	rial encoder (incre	mental)			
Vibration level			V5 or below			'	ed rotation speed: V10 speed and up to 5000	
Installation place, altitude and environment	For indoor use (fre	ee from direct sun	light), 1000m or be	low. locations with	out corrosive and	flamable gases, oi		,
Ambient temperature, humidity	-10 to +40°C, with		0 /-	. ,		3,		
Vibration resistance [m/s <sup>2</sup> ]			49				24.5	
Mass [kg]	0.45	0.55	1.2	1.8	3.4	4.4	5.2	6.3
( ) indicates brake-incorporated type.	(0.62)	(0.72)	(1.7)	(2.3)	(4.2)	(5.9)	(6.8)	(7.9)
Compliance with standards	UL/cUL (UL1004)	, CE marking (EN	60034-1, EN60034-	5), RoHS directive				

## ■Brake specifications (motor equipped with a brake)

Motor type		GYS500D5 -□□2-B	GYS101D5 <b>-□□2-B</b>	GYS201D5 <b>-□□2-B</b>	GYS401D5 <b>-□□2-B</b>	GYS751D5 -002-B	GYS102D5 <b>-□□2-B</b>	GYS152D5 -□□2-B	GYS202D5 -ПП2-В
Static friction torque	[N · m]	0.0	34	1.	27	2.45		6.86	
Rated DC voltage	[V]	DC24±10%							
Attraction time	[ms]	3	5	4	0	60		100	
Release time	[ms]	1	0	2	0	25		40	
Power consumption	[W]	6.1 (at	20 °C)	7.3 (at	20 °C)	8.5 (at 20 °C)		17.7 (at 20 °C)	

## Torque characteristics diagrams (at 3-phase 200 [V] or single-phase 230 [V] source voltage)

GYS500D5-□□2	GYS101D5-□□2	GYS201D5-□□2	GYS401D5-□□2
0.05kW	0.1kW	0.2kW	0.4kW
0.6 Acceleration/deceleration zone 0.4 Acceleration/deceleration zone 0.4 Acceleration/deceleration zone 0.5 Acceleration/deceleration zone 0.6 Acceleration/deceleration zone 0.7 Acceleration/deceleration zone 0.8 Acceleration/deceleration zone 0.9 Acceleration/deceleration zone 0.1 Acceleration/deceleration zone 0.1 Acceleration/deceleration zone 0.2 Acceleration/deceleration zone 0.3 Acceleration/deceleration zone 0.4 Acceleration/deceleration zone 0.5 Acceleration/deceleration zone 0.6 Acceleration/deceleration zone 0.7 Acceleration/deceleration zone 0.8 Acceleration/deceleration zone 0.9 Acceleration/deceleration zone 0.1 Acceleration/deceleration zone 0.1 Acceleration/deceleration zone 0.2 Acceleration/deceleration zone 0.3 Acceleration/deceleration zone 0.4 Acceleration/deceleration zone 0.5 Acceleration/deceleration zone 0.7 Acceleration/deceleration zone 0.8 Acceleration/deceleration zone 0.1 Acceleration/deceleratio	1.2 Acceleration/deceleration zone 1.0 Acceleration/deceleration zone 2. 0.6 Ontinuous operation zone 0.4 Ozoninuous operation zone 0.5 Ozoninuous operation zone 0.6 Ozoninuous operation zone 0.7 Ozoninuous operation zone 0.8 Ozoninuous operation zone 0.9 Ozoninuous operation zone 0.1 Ozoninuous operation zone 0.1 Ozoninuous operation zone	2.5 Acceleration/deceleration zone  2.0 Acceleration/deceleration zone  1.0 Continuous operation zone  0.0 1000 2000 3000 4000 5000 6000  Rotation speed [r/min]	4.0 Acceleration/deceleration zone  E 3.0 Continuous operation zone  1.0 Continuous operation zone  1.0 0 1000 2000 3000 4000 5000 6000 Rotation speed [r/min]
GYS751D5-002	GYS102D5-□□2	GYS152D5-□□2	GYS202D5-□□2
0.75kW	1.0kW	1.5kW	2.0kW
8.0 Acceleration/ deceleration zone  Continuous operation zone  0 0 0 000 2000 3000 4000 5000 6000	Acceleration/deceleration zone  Acceleration/deceleration zone  Continuous operation zone  Continuous operation zone  Description  Rotation speed [f/min]	Acceleration deceleration zone  E 10  S 8  Continuous operation zone  1 4  1 0  1 0 1000 2000 3000 4000 5000  Rotation speed (f/min)	Acceleration/deceleration zone  E 15 C Continuous operation zone  5 C Octinuous operation zone  Rotation speed [r/min]

These characteristics indicate typical values of each servomotor combined with the corresponding servo amplifier RYH series.

The rated torque indicates the value obtained when the servo amplifier is installed to the following aluminum heat sink.

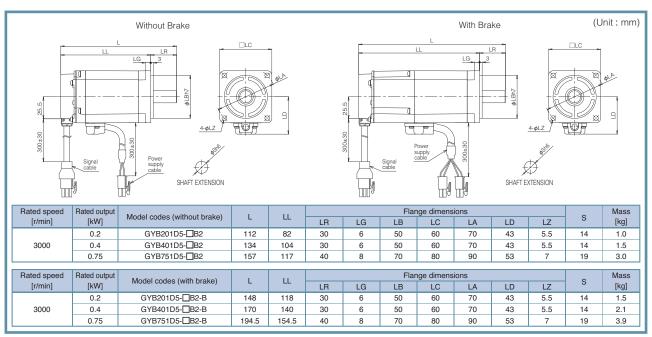
· Model GYS500D, 101D : 200×200×6 [mm] · Model GYS201D, 401D : 250×250×6 [mm] · Model GYS751D : 300×300×6 [mm]

· Model GYS102D, 152D, 202D : 350×350×8 [mm]

<sup>\*1</sup> The maximum rotation speed is 5000r/min when using the motor in combination with Fuji's gear head.
\*2 If the motor is used in the environment rated to IP67 protection degree, use the wiring connector suitable for the protection degree.

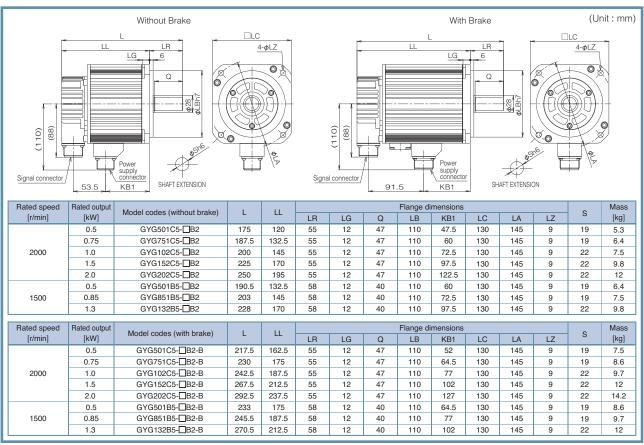


## **Middle Inertia GYB Motor [3000r/min]**



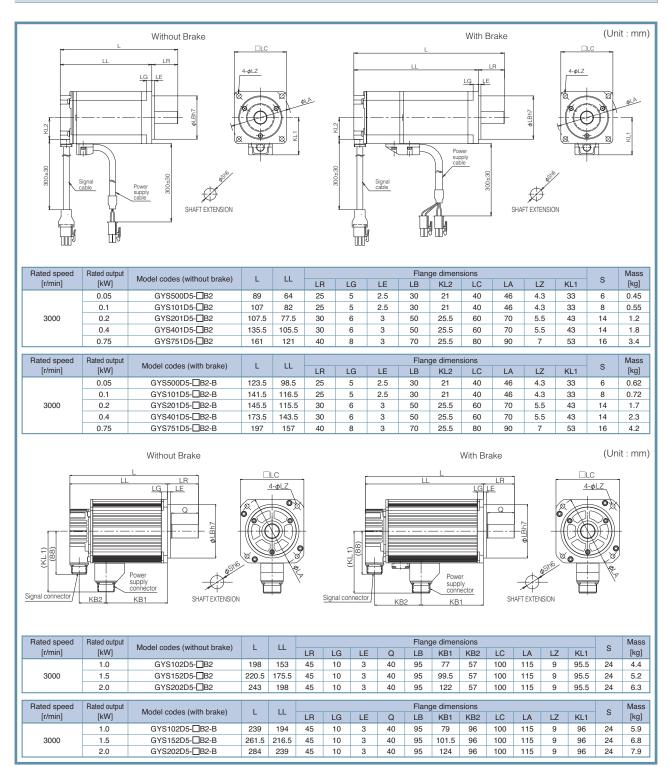
<sup>☐ :</sup> Encoder type R : INC(20bit), H : ABS(18bit)

## **Middle Inertia GYG Motor [2000r/min, 1500r/min]**



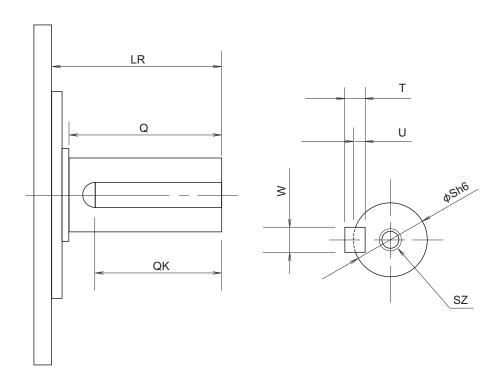
<sup>☐ :</sup> Encoder type R : INC(20bit), H : ABS(18bit)

## **III Ultra-low Inertia GYS Motor [3000r/min]**



 $<sup>\ \ \, \</sup>square : \mathsf{Encoder} \; \mathsf{type} \; \mathsf{R} \; \colon \mathsf{INC}(\mathsf{20bit}), \; \; \mathsf{H} \; \colon \mathsf{ABS}(\mathsf{18bit})$ 

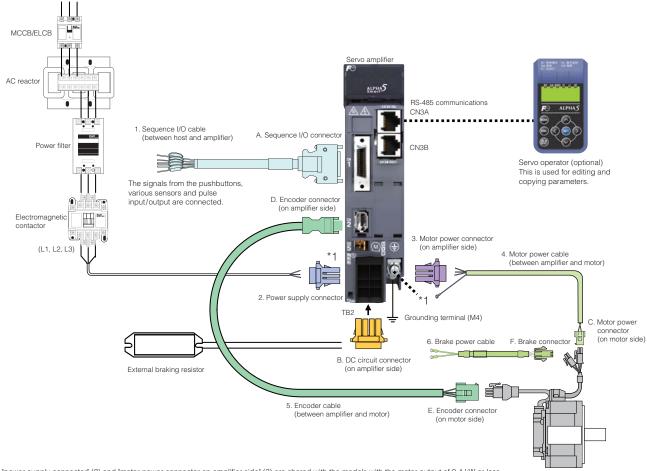




Motor type	LR	Q	QK	S	Т	U	W	SZ
GYB motor		<u>'</u>				'		
GYB201D5-□C2-□	30		14	14	5	3	5	M5 depth:8
GYB401D5-□C2-□								
GYB751D5-□C2-□	40		22	19	6	3.5	6	M6 depth:10
GYG motor 2000r/min								
GYG501C5-□C2-□	55	47	35	19	6	3.5	6	M6 depth:12
GYG751C5-□C2-□								
GYG102C5-□C2-□				22	7	4	8	M8 depth:16
GYG152C5-□C2-□								
GYG202C5-□C2-□								
GYG motor 1500r/min								
GYG501B5-□C2-□	58	40	30	19	6	3.5	6	M6 depth:12
GYG851B5-□C2-□								
GYG132B5-□C2-□				22	7	4	8	M8 depth:16
GYS motor								
GYS500D5-□A□-□*1	25	-	14	6	2	1.2	2	_
GYS101D5-□A□-□*1				8	3	1.8	3	_
GYS201D5-□C□-□	30		20	14	5	3	5	M5 depth:8
GYS401D5-□C□-□								
GYS751D5-□C2-□	40		30	16				
GYS102D5-□C2-□	45	40	32	24	7	4	8	M8 depth:16
GYS152D5-□C2-□								
GYS202D5-□C2-□								

<sup>\*1</sup> The shaft extension of the GYS and GYC motors of 0.1kW or less is not tapped.

## **EXECUTE** Configuration diagram



#### \*1: "power supply connector" (2) and "motor power connector on amplifier side" (3) are shared with the models with the motor output of 0.4 kW or less.

## **Example 2** Peripheral equipment

Input power	Rated speed	Motor output [kW]	Applicable servo amplifier type	Power capacity [kVA]	Input current [A]	Power filter	AC reactor	Wiring breaker MCCB	Earth leakage breaker ELCB	Electromagnetic contactor MC
Single-phase	3000r/min	0.05		0.1	0.7		ACR2-0.4A	BW32AAG-2P/3	EW32AAG-2P/3	
200V		0.1	RYH201F5-VV2	0.2	1.3	RNFTC06-20	ACR2-U.4A	BW3ZAAG-ZP/3	EW32AAG-2P/3	SC-03
		0.2		0.4	2.4		ACR2-0.75A	BW32AAG-2P/5	EW32AAG-2P/5	30-03
		0.4	RYH401F5-VV2	0.8	4.7	RNFTC10-20	ACR2-1.5A	BW32AAG-2P/10	EW32AAG-2P/10	1
		0.75	RYH751F5-VV2	1.5	8.6	RNFTC20-20	ACR2-2.2A	BW32AAG-2P/15	EW32AAG-2P/15	SC-0
	2000r/min	0.5	D) // ITE (EE ) // /0	1.0	5.8	RNFTC10-20	ACR2-1.5A	BW32AAG-2P/10	EW32AAG-2P/10	SC-03
		0.75	RYH751F5-VV2	1.5	8.6	RNFTC20-20	ACR2-2.2A	BW32AAG-2P/15	EW32AAG-2P/15	SC-0
	1500r/min	0.5	RYH751F5-VV2	1.0	5.8	RNFTC10-20	ACR2-1.5A	BW32AAG-2P/10	EW32AAG-2P/10	SC-03
3-phase	3000r/min	0.05		0.1	0.4					
200V		0.1	RYH201F5-VV2	0.2	0.7	RNFTC06-20	ACR2-0.4A	BW32AAG-3P/3	EW32AAG-3P/3	
		0.2		0.4	1.4					00.00
		0.4	RYH401F5-VV2	0.8	2.7		ACR2-0.75A	BW32AAG-3P/5	EW32AAG-3P/5	SC-03
		0.75	RYH751F5-VV2	1.5	5.0	DIJETO (O OO	ACR2-1.5A	BW32AAG-3P/10	EW32AAG-3P/10	1
		1.0	D) (1 1 4 5 0 5 5 ) A (0	2.0	6.6	RNFTC10-20		BW32AAG-3P/15	EW32AAG-3P/15	
		1.5	RYH152F5-VV2	2.9	9.8		ACR2-2.2A	BW32AAG-3P/20	EW32AAG-3P/20	+
		2.0	RYH202F5-VV2	3.9	13.0	RNFTC20-20	ACR2-3.7A	BW32AAG-3P/30	EW32AAG-3P/30	SC-4-1
	2000r/min	0.5	D) (1 175 155 1 0 10	1.0	3.3	RNFTC06-20	ACR2-0.75A	5,4,004.4.0.05,4.0	51100110 0B/10	
		0.75	RYH751F5-VV2	1.5	5.0	DIJETO (O OO	ACR2-1.5A	BW32AAG-3P/10	EW32AAG-3P/10	SC-03
		1.0	D) (1 1 4 5 0 5 5 1 0 4 0	2.0	6.6	RNFTC10-20	1000000	BW32AAG-3P/15	EW32AAG-3P/15	1
		1.5	RYH152F5-VV2	2.9	9.8	DUETO OO OO	ACR2-2.2A	BW32AAG-3P/20	EW32AAG-3P/20	00.4.4
		2.0	RYH202F5-VV2	3.9	13.0	RNFTC20-20	ACR2-3.7A	BW32AAG-3P/30	EW32AAG-3P/30	SC-4-1
	1500r/min	0.5	RYH751F5-VV2	1.0	3.3	RNFTC06-20	ACR2-0.75A	DIVIDAL LO ADUA	5,1,001.10.05,10	00.00
		0.85	RYH152F5-VV2	1.7	5.6	RNFTC10-20	ACR2-1.5A	BW32AAG-3P/10	BW32AAG-3P/10	SC-03
		1.3	RYH202F5-VV2	2.6	8.5	RNFTC20-20	ACR2-2.2A	BW32AAG-3P/15	EW32AAG-3P/15	SC-0



## **:::** Options

■ Basic option \* Prepare the optional items below when using the ALPHA5 Smart series.

Motor series	Rated speed	Rated output	Brake	Sequence I/O cable (between host and amplifier)	2. Power supply connector	B. DC circuit connector (on amplifier side)	Motor power connector     (on amplifier side)	4. Motor power cable (between amplifier and motor)	5. Encoder cable (between amplifier and motor)	6. Brake power cable
GYB motor	3000r/min	0.2kW,	W/o							_
		0.4kW	W/		WSK-S06P-F	WSK-R04P-F	*1			WSC-M02P02-E (2m) WSC-M02P05-E (5m) WSC-M02P10-E (10m WSC-M02P20-E (20m
		0.75kW	W/o						WSC-P06P02-E (2m) WSC-P06P05-E (5m) WSC-P06P10-E (10m) WSC-P06P20-E (20m)	-
			W/		WSK-S03P-F	*2	WSK-M03P-F			WSC-M02P02-E (2m) WSC-M02P05-E (5m) WSC-M02P10-E (10m WSC-M02P20-E (20m
GYG motor	2000r/min	0.5kW	W/o						WCC BOCBOE C (Em)	-
		to 2.0W	W/					Prepared by customer	WSC-P06P05-C (5m) WSC-P06P10-C (10m)	Prepared by customer
GYG motor	1500r/min	0.5kW	W/o	WSC-D26P02 *4				.,,	WSC-P06P20-C (20m)	_
		to 1.3kW	W/	WSC-D26P02-F *3						Prepared by customer
GYS motor	3000r/min	0.05kW to 0.4kW	W/o	WSC-D26P03						_
			W/		WSK-S06P-F	WSK-R04P-F	*1			WSC-M02P02-E (2m) WSC-M02P05-E (5m) WSC-M02P10-E (10m WSC-M02P20-E (20m
		0.75kW	W/o					WSC-M04P02-E (2m) WSC-M04P05-E (5m) WSC-M04P10-E (10m) WSC-M04P20-E (20m)		-
			W/							WSC-M02P02-E (2m)
	1.0kW to 2.0kW		WSK-S03P-F	*2	WSK-M03P-F			WSC-M02P05-E (5m) WSC-M02P10-E (10m WSC-M02P20-E (20m		
			W/o					Prepared by customer	WSC-P06P05-C (5m) WSC-P06P10-C (10m)	-
			W/					r repared by custoffier	WSC-P06P20-C (20m)	Prepared by customer

■ Connector kit options \* If the cables are fabricated by the customer, please use the connectors below.

Material	Detect consed	D	D I .	A. Sequence I/O	2. Power supply	B. DC circuit connector	3. Motor power connector	C. Motor power connector	Encoder (	connector	F. Brake connector
Motor series	nated speed	Rated output	Brake	connector	connector	(on amplifier side)	(on amplifier side)	(on motor side)	D. on amplifier side	E. on motor side	1. Drake connector
GYB motor	3000r/min	0.2kW,	W/o		WSK-S06P-F	WSK-R04P-F	*1				-
		0.4kW	W/		W3N-300F-F	Work-nu4F-F	3N-N04F-F			WSK-P09P-D	WSK-M02P-E
		0.75kW	W/o				WSK-M04P-E	-			
			W/								WSK-M02P-E
GYG motor	2000r/min	0.5kW	W/o		WSK-S03P-F	*2	WSK-M03P-F	WSK-M04P-CA			
		to 2.0W	W/		W3N-303F-F		WSK-WUSF-F	WSK-M06P-CA		WSK-P06P-C	_
GYG motor	1500r/min	0.5kW	W/o	WOL DOOD				WSK-M04P-CA	WSK-P06P-M	WSK-FUUF-C	
		to 1.3kW	W/	WSK-D26P				WSK-M06P-CA	WSK-FUUF-IVI		_
GYS motor	3000r/min	0.05kW	W/o		WSK-S06P-F	WSK-R04P-F	*1				-
		to 0.4kW	W/		W3K-300i -i	W31(-1104) -1	'	WSK-M04P-E		WSK-P09P-D	WSK-M02P-E
		0.75kW	W/o					W3I(-W04I -L		W5K-PU9P-D	-
			W/		WSK-S03P-F	*2	WSK-M03P-F				WSK-M02P-E
		1.0kW	W/o		***************************************		***************************************	WSK-M04P-CA		WOL BOOD O	
		to 2.0kW	W/					WSK-M06P-CA		WSK-P06P-C	_

 $<sup>^{\</sup>star}1:$  The connector is shared by the motor power (on the amplifiler side) and the power supply.

## ■External regenerative resistor options

Amplifier frame	Built-in	External brakin	g resistor type	External braking resistor type
RYH201F5-VV2	-	WSR-401	17W / 68 Ω	39 to 180
RYH401F5-VV2	-	VVOI 1-40 I	1747 00 12	39 to 90
RYH751F5-VV2	20W / 40 Ω	WSR-152	50W / 15 Ω	13 to 47
RYH152F5-VV2	20W / 15 Ω	W311-132	30VV / 13 12	8.2 to 27
RYH202F5-VV2	45W / 12 Ω	DB11-2	260W / 10 Ω	8.2 to 20
				•

## ■ABS backup battery

Amplifier	Optional battery type					
Ampinier	W/ battery case	Individual battery				
All	WSB-SC	WSB-S				

#### Other option

Specifications				Туре
For PC loader connection	RS-232C - RS-485 conversion adaptor	For connection of RS-485 port	-	NW0H-CNV
	Cable	of VV type servo amplifier *1	2m (connector at both ends)	WSC-PCL
Servo operator *1		_		WSP-51

<sup>\*1:</sup> Use a commercially-available USB cable (USB-A: USB-B, or USB-A: mini-B) when connecting the servo operator to PC. Use a commercially-available LAN cable when connecting the servo operation to the servo amplifier.

<sup>\*2:</sup> The connector is not necessary as it is included in the package of servo amplifier.

\*3: When connecting the open collector, Please use the sequence input/output cable for open collector (DC24V).

\*4: When connecting the open collector, Please use the sequence input/output cable for open collector (Outside DC24V).

## **Servo Amplifier**

Specification	ons						
Model	Control mode	Applicable motor output	Туре	Stock Type			
VV type	Position, speed and	General-purpose interface	Single	GYB, GYG, GYS	0.2kW, 0.1kW, 0.05kW	RYH201F5-VV2	0
	torque control	(pulse or analog voltage)	or 3-phase	motor	0.4kW	RYH401F5-VV2	0
	(With built-in linear	(Modbus-RTU)	200 to 240V		0.75kW, 0.5kW	RYH751F5-VV2	0
	positioning function)		3-phase		1.5kW, 1.0kW, 0.85kW	RYH152F5-VV2	0
			200 to 240V		2.0kW, 1.3kW	RYH202D5-VV2	0

## **Servo Motor**

Specification	ns							
Model	Voltage	Rated speed	Oil seal/shaft	Encoder	Brake	Rated output	Туре	Stock Type
GYB motor	200V	3000r/min	with oil seal /	20bit INC	W/o	0.2kW	GYB201D5-RG2	0
middle inertia)			with key, tapped			0.4kW	GYB401D5-RG2	0
						0.75kW	GYB751D5-RG2	0
					W/	0.2kW	GYB201D5-RG2-B	0
					0.4kW	GYB401D5-RG2-B	0	
					0.75kW	GYB751D5-RG2-B	0	
				18bit ABS	W/o	0.2kW	GYB201D5-HG2	Δ
					0.4kW	GYB401D5-HG2	Δ	
						0.75kW	GYB751D5-HG2	Δ
					W/	0.2kW	GYB201D5-HG2-B	Δ
						0.4kW	GYB401D5-HG2-B	Δ
						0.75kW	GYB751D5-HG2-B	Δ
			without oil seal /	20bit INC	W/o	0.2kW	GYB201D5-RC2	0
			with key, tapped			0.4kW	GYB401D5-RC2	0
			3. 11			0.75kW	GYB751D5-RC2	0
					W/	0.2kW	GYB201D5-RC2-B	0
						0.4kW	GYB401D5-RC2-B	0
					0.75kW	GYB751D5-RC2-B	0	
			18bit ABS	W/o	0.2kW	GYB201D5-HC2	Δ	
					0.4kW	GYB401D5-HC2	Δ	
					0.75kW	GYB751D5-HC2	Δ	
					W/	0.2kW	GYB201D5-HC2-B	Δ
						0.4kW	GYB401D5-HC2-B	Δ
						0.75kW	GYB751D5-HC2-B	Δ
YG motor	200V	2000r/min	with oil seal /	20bit INC	W/o	0.5kW	GYG501C5-RG2	0
niddle inertia)			with key, tapped			0.75kW	GYG751C5-RG2	0
						1.0kW	GYG102C5-RG2	0
						1.5kW	GYG152C5-RG2	0
						2.0kW	GYG202C5-RG2	0
					W/	0.5kW	GYG501C5-RG2-B	0
						0.75kW	GYG751C5-RG2-B	0
						1.0kW	GYG102C5-RG2-B	0
						1.5kW	GYG152C5-RG2-B	0
						2.0kW	GYG202C5-RG2-B	0
				18bit ABS	W/o	0.5kW	GYG501C5-HG2	Δ
						0.75kW	GYG751C5-HG2	Δ
					1.0kW	GYG102C5-HG2	Δ	
						1.5kW	GYG152C5-HG2	Δ
						2.0kW	GYG202C5-HG2	Δ
					W/	0.5kW	GYG501C5-HG2-B	Δ
						0.75kW	GYG751C5-HG2-B	Δ
				1.0kW	GYG102C5-HG2-B	Δ		
						1.5kW	GYG152C5-HG2-B	Δ
						2.0kW	GYG202C5-HG2-B	Δ

Note: Please contact our sales, if the models outside the above are needed.

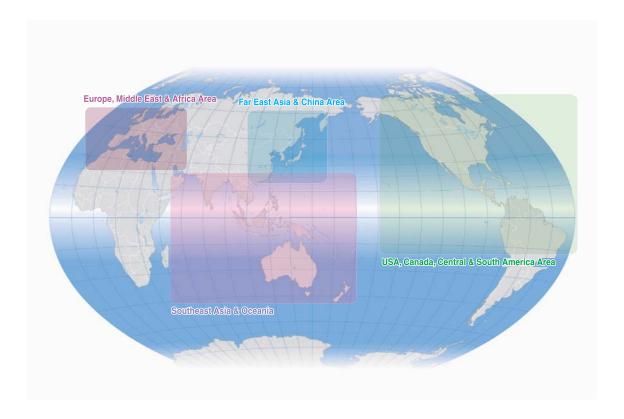


## **Servo Motor**

Specification	าร						Туре	Stock Type
/lodel	Voltage	Rated speed	Oil seal/shaft	Encoder	Brake	Rated output	туре	этоск туре
YS motor	200V	3000r/min	without oil seal /	20bit INC	W/o	0.05kW	GYS500D5-RA2*	0
tra-low inertia)			with key, tapped			0.1kW	GYS101D5-RA2*	0
			(* GYS motor of 0.1kW or			0.2kW	GYS201D5-RC2	0
			less is not tapped.)			0.4kW	GYS401D5-RC2	0
						0.75kW	GYS751D5-RC2	0
						1.0kW	GYS102D5-RC2	0
						1.5kW	GYS152D5-RC2	0
						2.0kW	GYS202D5-RC2	0
		W/ 0.1	0.05kW	GYS500D5-RA2-B*	0			
						0.1kW	GYS101D5-RA2-B*	0
						0.2kW	GYS201D5-RC2-B	0
					0.4kW	GYS401D5-RC2-B	0	
					0.75kW	GYS751D5-RC2-B	0	
					1.0kW	GYS102D5-RC2-B	0	
					1.5kW	GYS152D5-RC2-B	0	
						2.0kW	GYS202D5-RC2-B	0
				18bit ABS W/o	W/o	0.05kW	GYS500D5-HA2*	Δ
						0.1kW	GYS101D5-HA2*	Δ
					0.2kW	GYS201D5-HC2	Δ	
						0.4kW	GYS401D5-HC2	Δ
					0.75kW	GYS751D5-HC2	Δ	
						1.0kW	GYS102D5-HC2	Δ
						1.5kW	GYS152D5-HC2	Δ
						2.0kW	GYS202D5-HC2	Δ
					W/	0.05kW	GYS500D5-HA2-B*	Δ
						0.1kW	GYS101D5-HA2-B*	Δ
						0.2kW	GYS201D5-HC2-B	Δ
						0.4kW	GYS401D5-HC2-B	Δ
						0.75kW	GYS751D5-HC2-B	Δ
						1.0kW	GYS102D5-HC2-B	Δ
						1.5kW	GYS152D5-HC2-B	Δ
					2.0kW	GYS202D5-HC2-B	Δ	

Note: Please contact our sales, if the models outside the above are needed.

©: Standard △: Order-made



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## III Please take the following items into consideration when placing your order.

When requesting an estimate and placing your orders for the products included in these materials, please be aware that any items such as specifications which are not specifically mentioned in the contract, catalog, specifications or other materials will be as mentioned below.

In addition, the products included in these materials are limited in the use they are put to and the place where they can be used, etc., and may require periodic inspection. Please confirm these points with your sales representative or directly with this company.

Furthermore, regarding purchased products and delivered products, we request that you take adequate consideration of the necessity of rapid receiving inspections and of product management and maintenance even before receiving your products.

#### 1. Free of Charge Warranty Period and Warranty Range

#### 1-1 Free of charge warranty period

- (1) The product warranty period is "1 year from the date of purchase" or 24 months from the manufacturing date imprinted on the name place, whichever date is earlier.
- (2) However, in cases where the use environment, conditions of use, use frequency and times used, etc., have an effect on product life, this warranty period may not apply.
- (3) Furthermore, the warranty period for parts restored by Fuji Electric's Service Department is "6 months from the date that repairs are completed."

#### 1-2 Warranty range

- (1) In the event that breakdown occurs during the product's warranty period which is the responsibility of Fuji Electric, Fuji Electric will replace or repair the part of the product that has broken down free of charge at the place where the product was purchased or where it was delivered. However, if the following cases are applicable, the terms of this warranty may not apply.
  - 1) The breakdown was caused by inappropriate conditions, environment, handling or use methods, etc. which are not specified in the catalog, operation manual, specifications or other relevant documents.
  - 2) The breakdown was caused by the product other than the purchased or delivered Fuji's product.
  - 3) The breakdown was caused by the product other than Fuji's product, such as the customer's equipment or software design, etc.
  - 4) Concerning the Fuji's programmable products, the breakdown was caused by a program other than a program supplied by this company, or the results from using such a program.
  - 5) The breakdown was caused by modifications or repairs affected by a party other than Fuji Electric.
  - 6) The breakdown was caused by improper maintenance or replacement using consumables, etc. specified in the operation manual or catalog, etc.
  - 7) The breakdown was caused by a chemical or technical problem that was not foreseen when making practical application of the product at the time it was purchased or delivered.
  - 8) The product was not used in the manner the product was originally intended to be used.
  - 9) The breakdown was caused by a reason which is not this company's responsibility, such as lightning or other disaster.
- (2) Furthermore, the warranty specified herein shall be limited to the purchased or delivered product alone.
- (3) The upper limit for the warranty range shall be as specified in item (1) above and any damages (damage to or loss of machinery or equipment, or lost profits from the same, etc.) consequent to or resulting from breakdown of the purchased or delivered product shall be excluded from coverage by this warranty.

#### 1-3. Trouble diagnosis

As a rule, the customer is requested to carry out a preliminary trouble diagnosis. However, at the customer's request, this company or its service network can perform the trouble diagnosis on a chargeable basis. In this case, the customer is asked to assume the burden for charges levied in accordance with this company's fee schedule.

#### 2. Exclusion of Liability for Loss of Opportunity, etc.

Regardless of whether a breakdown occurs during or after the free of charge warranty period, this company shall not be liable for any loss of opportunity, loss of profits, or damages arising from special circumstances, secondary damages, accident compensation to another company, or damages to products other than this company's products, whether foreseen or not by this company, which this company is not be responsible for causing.

## 3. Repair Period after Production Stop, Spare Parts Supply Period (Holding Period)

Concerning models (products) which have gone out of production, this company will perform repairs for a period of 7 years after production stop, counting from the month and year when the production stop occurs. In addition, we will continue to supply the spare parts required for repairs for a period of 7 years, counting from the month and year when the production stop occurs. However, if it is estimated that the life cycle of certain electronic and other parts is short and it will be difficult to procure or produce those parts, there may be cases where it is difficult to provide repairs or supply spare parts even within this 7-year period. For details, please confirm at our company's business office or our service office.

#### 4. Transfer Rights

In the case of standard products which do not include settings or adjustments in an application program, the products shall be transported to and transferred to the customer and this company shall not be responsible for local adjustments or trial operation.

#### **5. Service Contents**

The cost of purchased and delivered products does not include the cost of dispatching engineers or service costs. Depending on the request, these can be discussed separately.

#### 6. Applicable Scope of Service

Please inquiry the supplier or Fuji Electric China for details of above.



## **SAFETY PRECAUTIONS**

- 1. This catalog is intended for use in selecting required servo systems. Before actually using these products, carefully read their instruction manuals and understand their correct usage.
- 2. Products described in this catalog are neither designed nor manufactured for combined use with a system or equipment that will affect human lives.
  - If you are considering using these products for special purposes, such as atomic energy control, aerospace, medical application, or traffic control, please consult our sales office.
- 3. If you use our product with equipment that is expected to cause serious injury or damage to your property in case of failure, be sure to take appropriate safety measures for the equipment.

# Fuji Electric Co., Ltd.

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